## Problem 1.

(12 points)

(a) Solve the given vector equation for  $\alpha$ , or explain why no solution exists:

	1		3		[-1]	
$\alpha$	2	+4	4	=	0	
	$\begin{bmatrix} 1\\ 2\\ -1 \end{bmatrix}$		2		4	
	L _					

## **A:**

Performing the indicated operations we obtain the vector equations (2 points)

$$\begin{bmatrix} \alpha \\ 2\alpha \\ -\alpha \end{bmatrix} + \begin{bmatrix} 12 \\ 16 \\ 8 \end{bmatrix} = \begin{bmatrix} \alpha+12 \\ 2\alpha+16 \\ -\alpha+8 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 4 \end{bmatrix}$$

Thus, if a solution  $\alpha$  exists  $\alpha$  must satisfy the three equations:

$$\alpha + 12 = -1$$
$$2\alpha + 16 = 0$$
$$-\alpha + 8 = 4$$

which leads to  $\alpha = -13$ ,  $\alpha = -8$  and  $\alpha = 4$ . since  $\alpha$  cannot simultaneously have three different values, there is no solution to the original vector equation. (2 points)

(b) For the matrix 
$$A = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$$
, compute  $A^2, A^3, A^4$ .  
**A:** (3 points)  $A^2 = \begin{bmatrix} 1 & -2 \\ 0 & 1 \end{bmatrix}, A^3 = \begin{bmatrix} 1 & -3 \\ 0 & 1 \end{bmatrix}, A^4 = \begin{bmatrix} 1 & -4 \\ 0 & 1 \end{bmatrix}$ .  
(c) Find the solution set of the following linear system

$$3x_1 + 4x_2 - x_3 + 2x_4 = 6x_1 - 2x_2 + 3x_3 + x_4 = 210x_2 - 10x_3 - x_4 = 1$$

#### **A**:

The augmented matrix row-reduces to (3 points)

Row 3 represents the equation 0 = 1, so the original system has no solutions. The solution set is the empty set  $\emptyset$ . (2 points)

# Problem 2.(8 points)

Define two mappings  $T: \mathbb{R}^2 \to \mathbb{R}^2$  and  $S: \mathbb{R}^2 \to \mathbb{R}^2$  by

$$T\left(\left[\begin{array}{c}x\\y\end{array}\right]\right) = \left[\begin{array}{c}2x+y\\0\end{array}\right], S\left(\left[\begin{array}{c}x\\y\end{array}\right]\right) = \left[\begin{array}{c}x+y\\xy\end{array}\right]$$

Determine whether T, S, are linear transformations.

**A**:

To prove that T is a linear transformation, note that for any  $\mathbf{x}, \mathbf{y} \in \mathbb{R}^2$ , if we write

$$\mathbf{x} = \left[ \begin{array}{c} x_1 \\ x_2 \end{array} \right], \mathbf{y} = \left[ \begin{array}{c} y_1 \\ y_2 \end{array} \right]$$

then we have (4 points)

$$T(\mathbf{x} + \mathbf{y}) = T\left( \begin{bmatrix} x_1 + y_1 \\ x_2 + y_2 \end{bmatrix} \right) = \begin{bmatrix} 2(x_1 + y_1) + (x_2 + y_2) \\ 0 \end{bmatrix}$$
$$= \begin{bmatrix} 2x_1 + x_2 \\ 0 \end{bmatrix} + \begin{bmatrix} 2y_1 + y_2 \\ 0 \end{bmatrix} = T(\mathbf{x}) + T(\mathbf{y})$$

To prove that S is not a linear transformation, observe that (2 points)

$$S\left(\left[\begin{array}{c}1\\0\end{array}\right]\right) = \left[\begin{array}{c}1\\0\end{array}\right], \quad S\left(\left[\begin{array}{c}0\\1\end{array}\right]\right) = \left[\begin{array}{c}1\\0\end{array}\right], \quad S\left(\left[\begin{array}{c}1\\1\end{array}\right]\right) = \left[\begin{array}{c}2\\1\end{array}\right]$$

Therefore, (2 points)

$$S\left(\left[\begin{array}{c}1\\0\end{array}\right]+\left[\begin{array}{c}0\\1\end{array}\right]\right) = S\left(\left[\begin{array}{c}1\\1\end{array}\right]\right) = \left[\begin{array}{c}2\\1\end{array}\right] \neq \left[\begin{array}{c}2\\0\end{array}\right] = \left[\begin{array}{c}1\\0\end{array}\right] + \left[\begin{array}{c}1\\0\end{array}\right]$$
$$= S\left(\left[\begin{array}{c}1\\0\end{array}\right]\right) + S\left(\left[\begin{array}{c}0\\1\end{array}\right]\right)$$

Thus it is not the case that  $S(\mathbf{x} + \mathbf{y}) = S(\mathbf{x}) + S(\mathbf{y})$  for all  $\mathbf{x}, \mathbf{y} \in \mathbb{R}^2$ . It follows that S cannot be a linear transformation.

### **Problem** 3.(20 points)

True or False: If True, explain why. If False, give an explicit numerical example for which the statement does not hold.

(a) If the augmented matrix of the system  $A\mathbf{x} = \mathbf{b}$  has a pivot in the last column, then the system  $A\mathbf{x} = \mathbf{b}$  has no solution.

A: True. (2 points) Because there is a row of the form  $[0 \ 0 \ \cdots \ 0 \ | \ b]$  with  $b \neq 0$  in the augmented matrix, the linear system cannot have a solution.

(b) If for some matrix A, and some vectors  $\mathbf{x}, \mathbf{b}$ , we have  $A\mathbf{x} = \mathbf{b}$ , then  $\mathbf{b}$  is a linear combination of the column vectors of A.

A: True. (2 points) This follows that  $A\mathbf{x}$  is a linear combination of the columns of A. (3 points)

(c) Given  $2 \times 2$  matrices A, B, C, if AB = AC and A is not a zero matrix, then B = C. **A:** False (2 points). Take  $A = B = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$  and C = 0. (3 points)

(d) If a set of n vectors in  $\mathbb{R}^m$  are linearly dependent, then any vector in this set can be represented by the linear combination of other n-1 vectors (n > 1).

**A:** False. (2 points) Consider  $\mathbf{a}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ ,  $\mathbf{a}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ ,  $\mathbf{a}_3 = \begin{bmatrix} 0 \\ 2 \end{bmatrix}$ . Then  $\{\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3\}$  are linearly dependent, but  $\mathbf{a}_1$  cannot be represented as the linear combination of  $\mathbf{a}_2, \mathbf{a}_3$ . (3 points)

## Problem 4.

(10 points) For a real number c, consider the linear system

$$x_1 + x_2 + cx_3 + x_4 = c$$
  
-x<sub>2</sub> + x<sub>3</sub> + 2x<sub>4</sub> = 0  
$$x_1 + 2x_2 + x_3 - x_4 = -c$$

a) For what c, does the linear system have a solution? A:

Let us find the REF of the augmented matrix (3 points)

ſ	1	1	c	1	c		[1]	1	c	1	c		1	1	c	1	
	0	-1	1	2	1	$\sim \rightarrow$	0	$^{-1}$	1	2	0	$\sim \rightarrow$	0	$^{-1}$	1	2	0
	. 1	2	1	-1	-c		0	1	1-c	-2	-2c		0	0	2-c	0	$\begin{bmatrix} c \\ 0 \\ -2c \end{bmatrix}$

Each of the two row has a pivot. Thus the linear system has a solution if and only if  $c \neq 2$ . (2 points)

b) Find the solution set when c = 0.

A: When c = 0, this is a homogeneous linear system. (1 points) the REF of the unaugmented matrix is (2 points)

The free variable is  $x_4$  and so the solution set is (2 points)

$$\left\{ \left[ \begin{array}{c} -3x_4\\2x_4\\0\\x_4 \end{array} \right] \middle| x_4 \in \mathbb{R} \right\}.$$

Problem 5.

(10 points) Suppose  $T: \mathbb{R}^3 \to \mathbb{R}^3$  satisfies

$$T\left(\left[\begin{array}{c}0\\1\\0\end{array}\right]\right) = \left[\begin{array}{c}1\\2\\-1\end{array}\right], \quad T\left(\left[\begin{array}{c}1\\1\\1\end{array}\right]\right) = \left[\begin{array}{c}0\\0\\0\end{array}\right]$$

and the image of T contains at least two linearly independent vectors. Which of the following are a possible standard matrix of T?

a) 
$$\begin{bmatrix} -1 & 1 & 0 \\ -2 & 2 & 0 \\ 1 & -1 & 0 \end{bmatrix}$$
 b)  $\begin{bmatrix} 1 & 1 & -2 \\ 2 & 2 & -4 \\ 1 & -1 & -2 \end{bmatrix}$ 

c) 
$$\begin{bmatrix} 1 & 1 & -2 \\ 0 & 2 & -2 \\ 0 & -1 & 1 \end{bmatrix}$$
 d)  $\begin{bmatrix} 1 & 1 & -2 \\ 0 & 2 & -2 \\ 2 & -1 & -1 \end{bmatrix}$  e)  $\begin{bmatrix} -1 & 1 & 0 \\ 0 & 2 & -2 \\ 0 & -1 & 0 \end{bmatrix}$   
second column must be

A: First, the

$$\begin{bmatrix} 1\\ 2\\ -1 \end{bmatrix}$$

which is satisfied by all matrices. (2 points)

Use the linearity, we find that the standard matrix A must satisfy

$$A\begin{bmatrix}1\\1\\1\end{bmatrix} = \begin{bmatrix}0\\0\\0\end{bmatrix}.$$

This is satisfied by a) c) d) but not b) e) (2 points)

The image of T, i.e. the span of the vectors in a) is

$$\left\{ c \left[ \begin{array}{c} -1 \\ -2 \\ 1 \end{array} \right] \middle| c \in \mathbb{R} \right\}$$

which does not contain two linearly independent vectors. (3 points)

The first two columns of c) d) are already linearly independent. (3 points) So the answer is c) d).