1.

(1) (T) There exist invertible matrices E and F such that $E\begin{pmatrix} 1 & -2 \\ -2 & 4 \end{pmatrix}F = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$.

The two columns are scalar multiples of each other, so $\begin{pmatrix} 1 & -2 \\ -2 & 4 \end{pmatrix}$ has rank 1. Thus it can be transformed into $\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$ by elementary row/column operations (Theorem 3.6). Hence there exist E and F as above (representing elementary row and column operations, respectively).

(2) (F) Let $A \in M_{n \times n}(\mathbb{R})$. If det(-A) = det(A) then A is not invertible.

If n = 2 and $A = I_2$ then $det(-I_2) = det(I_2) = 1$ but I_2 is invertible.

(3) (T) Let T be a linear operator on a finite-dimensional vector space V and W be a T-invariant subspace of V. If T is diagonalizable, then the characteristic polynomial of T_W splits.

Since T is diagonalizable, $ch_T(t)$ splits. As $ch_{T_W}(t)$ divides $ch_T(t)$, we see that $ch_{T_W}(t)$ must split as well.

(4) (F) Let T be a nonzero linear operator on a finite-dimensional vector space V. Let $v \in V$. Then the T-cyclic subspace generated by v is the same as the T-cyclic subspace generated by T(v).

If $V = \mathbb{R}^2$ and T(x, y) = y and v = (1, 0) then the *T*-cyclic subspace generated by v is \mathbb{R}^2 but the *T*-cyclic subspace generated by T(v) is $\{0\}$.

2. (16 pts) Let A be an $m \times n$ matrix and B an $n \times p$ matrix (with entries in F). Suppose AB has rank m. Determine, with proof, the rank of A.

We know that the rank of a matrix is at most the number of its rows or columns, so in particular rank $(A) \leq m$. Also the rank of a product of matrices is at most the rank of each individual matrix, so in particular rank $(AB) \leq \operatorname{rank}(A)$. Combining these facts with the fact that rank(AB) = m, we have

$$m = \operatorname{rank}(AB) \le \operatorname{rank}(A) \le m,$$

which implies $\operatorname{rank}(A) = m$. \Box

Alternative proof:

Translating the statement of the problem from matrices to linear maps, we have

 $L_A: F^n \to F^m$ and $L_B: F^p \to F^n$ and so $L_{AB} = L_A L_B: F^p \to F^m$.

Recall that the rank of a matrix is equal to the rank of the associated linear transformation. The rank of AB being equal to m is equivalent to L_{AB} being onto, which implies L_A is onto, and this is equivalent to A having rank m. \Box

3. (16 pts) By any legitimate method, solve the system of linear equations over \mathbb{R}

(If no solution exists, explain. If there are solutions, describe the general solution.)

[See a separate note.]

4. Let $T: V \to V$ be a linear operator on a finite dimensional vector space V such that $T^2 = T$.

(1) Show that the only possible eigenvalues of T are 1 and 0.

(2) Prove that T is diagonalizable. (Hint: For every $v \in V$, show that $T(v) \in E_1$ and $v - T(v) \in E_0$. Then try to apply one of the diagonalizability criteria.)

(1) Suppose $T(v) = \lambda v$ with $\lambda \in F, v \neq 0$. Then

$$T^{2}(v) = T(T(v)) = T(\lambda v) = \lambda T(v) = \lambda(\lambda v) = \lambda^{2} v.$$

The assumption in the problem says $T^2 = T$, so we have a chain of deductions

$$T^{2}(v) = T(v) \quad \Rightarrow \quad \lambda^{2}v = \lambda v \quad \Rightarrow \quad (\lambda^{2} - \lambda)v = 0 \quad \Rightarrow \quad \lambda^{2} - \lambda = 0 \quad \Rightarrow \quad \lambda(\lambda - 1) = 0.$$

(The second last arrow is valid because $v \neq 0$.) Therefore $\lambda = 0$ or $\lambda = 1$.

(2) One criterion is that T is diagonalizable if V is spanned by the eigenspaces. In our case, by (1), it suffices to observe that V is spanned by E_0 and E_1 .

For every $v \in V$, we have T(T(v)) = T(v), so clearly $T(v) \in E_1$. Moreover $T(v - T(v)) = T(v) - T^2(v) = 0$ so

$$v - T(v) \in N(T) = E_0.$$

This implies that

$$v = \underbrace{(v - T(v))}_{\in E_0} + \underbrace{T(v)}_{\in E_1} \in \operatorname{span}(E_0 \cup E_1).$$

By the criterion, T is diagonalizable. \Box

5. For the two matrices below, considered over \mathbb{R} , (1) determine whether it is diagonalizable and (2) if it is, then find an invertible matrix Q and a diagonal matrix D such that $D = Q^{-1}AQ$.

(a)
$$A = \begin{pmatrix} 3 & 2 \\ 2 & 3 \end{pmatrix}$$
, (b) $A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$

[See a separate note.]

3. (16 pts) By any legitimate method, solve the system of linear equations over \mathbb{R}

(If no solution exists, explain. If there are solutions, describe the general solution.)

the new system of equations is

$$\begin{cases}
x_1 + 3x_4 = 2 & x_1 = 2 - 3t \\
x_2 + 5x_4 = 5 & x_2 = 5 - 5t \\
x_3 - x_4 = -1 & x_3 = -1 + t
\end{cases}$$

$$\therefore \text{ general sol is} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 2 - 3t \\ 5 - 5t \\ -1 + t \\ t \end{pmatrix} = \begin{pmatrix} 2 \\ 5 \\ -1 \\ 0 \end{pmatrix} + \begin{pmatrix} -3 \\ -5 \\ 1 \\ 1 \end{pmatrix} t$$

$$eifter is correct. Equation is even is correct. Equation is correct. Equation is correct. Equation is correct. Equation is a sol is not unique. Any sol of the form so that, where is correct. If a is " Ax=0. It is five variable (could have another name) is considered correct.$$

5. For the two matrices below, considered over \mathbb{R} , (1) determine whether it is diagonalizable and (2) if it is, then find an invertible matrix Q and a diagonal matrix D such that $D = Q^{-1}AQ$.

(a)
$$A = \begin{pmatrix} 3 & 2 \\ 2 & 3 \end{pmatrix}$$
, (b) $A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$.
(1)
Sol (a) $ch_{A}(t) = det(A-tI) = det\begin{pmatrix} 3-t & 2 \\ 2 & 3-t \end{pmatrix}$
 $= (3-t)^{2} - 4 = t^{2} - 6t + 5 = (t-1)(t-5)$
 \therefore Eigenvalues are 1, 5.
 $= A$ is diaponalizable (since 2x2 motrix hor)

(2) We find eigenvector for
$$\lambda = 1, 5$$
.

$$\lambda = 1 \quad \in_{I} = \begin{cases} \begin{pmatrix} X_{1} \\ X_{2} \end{pmatrix} \in \mathbb{R}^{2} : \begin{pmatrix} A - I \end{pmatrix} \begin{pmatrix} X_{1} \\ X_{2} \end{pmatrix} = 0 \\ \begin{pmatrix} 2 - 2 \end{pmatrix} \\ \begin{pmatrix} 2 - 2 \end{pmatrix} \\ \end{pmatrix} = \begin{cases} \begin{pmatrix} X_{1} \\ X_{2} \end{pmatrix} : & 2x_{1} + 2x_{2} = 0 \\ \begin{pmatrix} 2 - 2 \end{pmatrix} \\ \end{pmatrix} = Span \left\{ \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right\}.$$

$$\lambda = S \quad \in_{G} = \begin{cases} \begin{pmatrix} X_{1} \\ X_{2} \end{pmatrix} : & (A - SI) \begin{pmatrix} X_{1} \\ X_{2} \end{pmatrix} = 0 \\ \begin{pmatrix} -2 & 2 \\ 2 - 2 \end{pmatrix} \\ = \begin{cases} \begin{pmatrix} X_{1} \\ X_{2} \end{pmatrix} : & -2x_{1} + 2X_{2} = 0 \\ \end{pmatrix} = Span \left(\begin{pmatrix} 1 \\ 1 \\ \end{pmatrix} \right)$$

$$Putting \quad eigenvectors are colours of Q, we constant Q = \begin{pmatrix} (1 \\ -1 \end{pmatrix} \\ \begin{pmatrix} 1 \\ 1 \\ \end{pmatrix} \\ \text{output line eigenvectors are colours of Q, we constant Q = \begin{pmatrix} (1 \\ -1 \end{pmatrix} \\ \begin{pmatrix} 1 \\ -1 \end{pmatrix} \\ \text{odden } Q^{-1}AQ = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \\ \text{odden } S \\ \text{odden }$$

for A: n×n - $A:n \times n$ Since dim $E_1 < m_1$, A is not diaponalizable.