1. (20 points) The following values from the 8-point DFT of a length-8 real sequence x[n] are known:

$$X[0] = 3, \ X[2] = 0.5 - 4.5j, \ X[4] = 5, \ X[5] = 3.5 + 3.5j, \ X[7] = -2.5 - 7j.$$

- a) (5 points) Find the missing values X[1], X[3], X[6].
- b) (5 points) Evaluate x[0].
- c) (10 points) Find the 4-point DFT of the length-4 sequence w[n] given by:

$$w[n] = x[n] + x[n+4]$$
 $n = 0, 1, 2, 3.$

Hint: Derive a general formula that relates W[k] to X[k] so you don't have to calculate x[n] and w[n].

(Sam)

a). Because x[n] is real,

$$X[1] = X^*[7] = -2.5 + 7j \tag{1}$$

$$X[3] = X^*[5] = 3.5 - 3.5j \tag{2}$$

$$X[6] = X^*[2] = 0.5 + 4.5j \tag{3}$$

b).

$$x[0] = \frac{1}{8} \sum_{k=0}^{7} X[k] \tag{4}$$

$$= \frac{1}{8}(3 + 2(-2.5) + 2(0.5) + 2(3.5) + 5)$$

$$= \frac{11}{8}$$
(6)

$$=\frac{11}{8}\tag{6}$$

c).

$$W[k] = \sum_{n=0}^{3} (x[n] + x[n+4])e^{\frac{-2\pi}{4}kn}$$
 (7)

$$=\sum_{n=0}^{7} x[n]e^{\frac{-2\pi}{4}kn} \tag{8}$$

$$=X[2k] \tag{9}$$

Thus

$$W[0] = X[0] = 3 \tag{10}$$

$$W[1] = X[2] = 0.5 - 4.5j (11)$$

$$W[2] = X[4] = 5 (12)$$

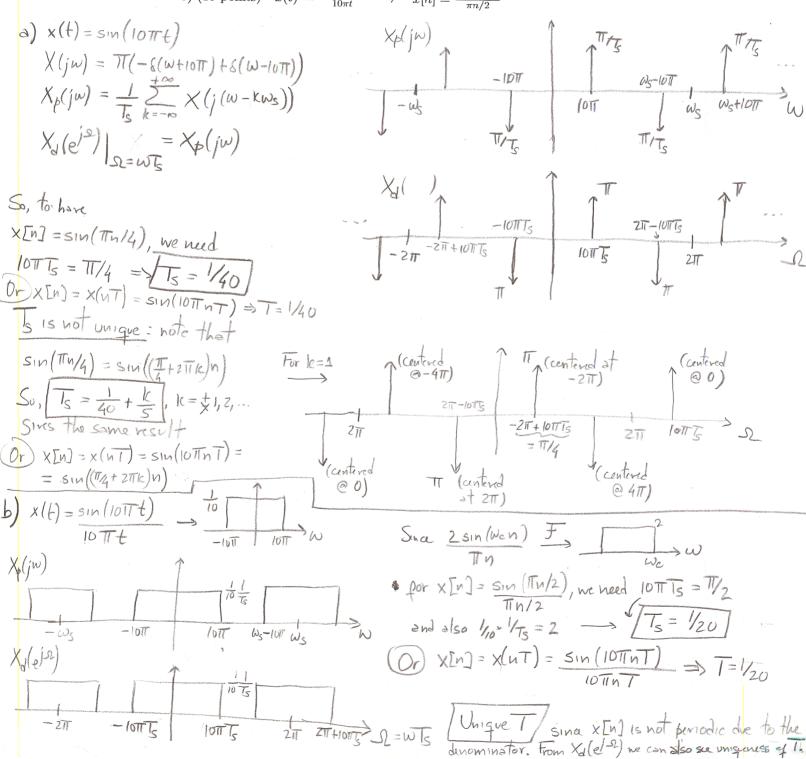
$$W[3] = X[6] = 0.5 + 4.5j (13)$$



2. (20 points) The continuous-time signals x(t) below are sampled to generate the corresponding discrete-time signals x[n]. Specify a choice for the sampling period T consistent with each pair. In addition, indicate whether the choice of T is unique. If not, specify a second choice of T.

a) (10 points)
$$x(t) = \sin(10\pi t) \to x[n] = \sin(\pi n/4)$$

b) (10 points)
$$x(t) = \frac{\sin(10\pi t)}{10\pi t} \rightarrow x[n] = \frac{\sin(\pi n/2)}{\pi n/2}$$

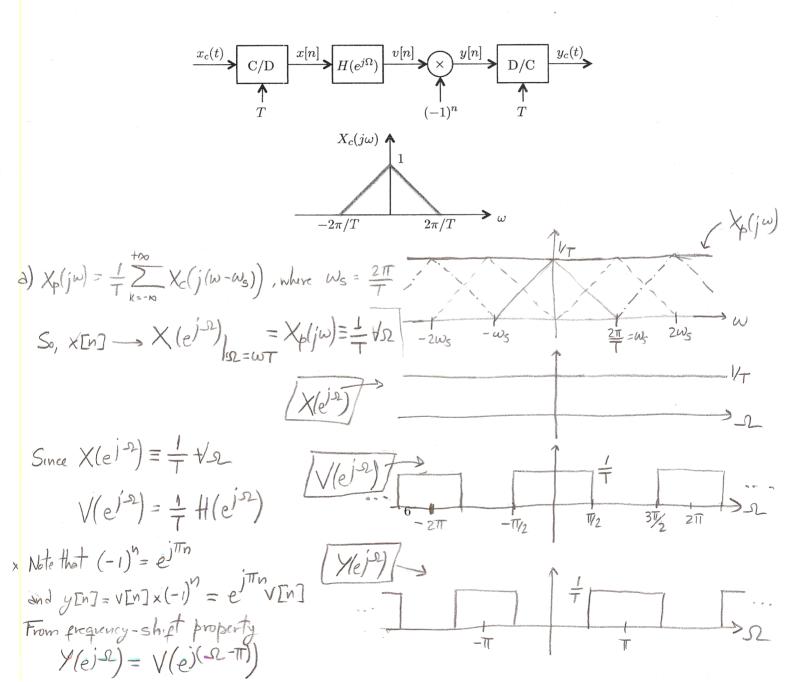


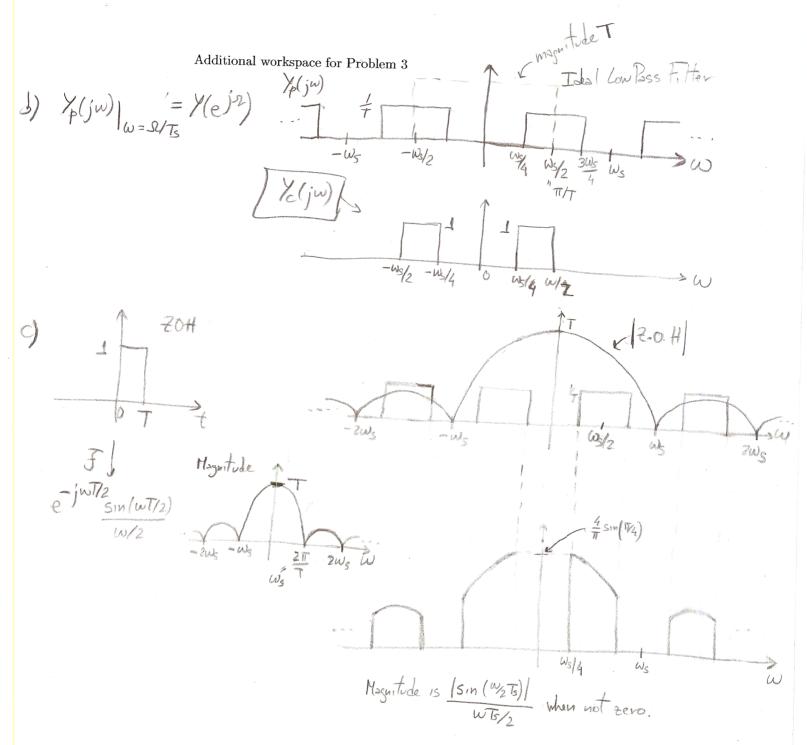
3. (20 points) Consider the system below, where

$$H(e^{j\Omega}) = \begin{cases} 1, & |\Omega| < \pi/2 \\ 0, & \pi/2 < |\Omega| \le \pi. \end{cases}$$

and assume the CTFT of the input, $X_c(j\omega)$, is as shown below.

- a) (10 points) Sketch the DTFT for x[n], v[n] and y[n].
- b) (5 points) Sketch the CTFT for the output, $Y_c(j\omega)$, assuming an ideal D/C converter.
- c) (5 points) Sketch the magnitude $|Y_c(j\omega)|$ assuming, this time, a zero-order hold D/C converter.





 $4.\,$ a) (15 points) Specify the transfer function of a stable and causal LTI system whose frequency response has the magnitude:

$$|H(j\omega)| = \frac{1}{\sqrt{1+\omega^4}}.$$

- b) (5 points) Is the answer to part (a) unique? If not, specify another stable and causal LTI system whose frequency response has the same magnitude but a different phase.
- This is a Butterworth filter (Lecture 15) with wc=1, N=2. Therefore, poles:

$$Su2 = -4 \mp i \frac{1}{2}$$

$$H(s) = \frac{1}{(s+t_2-jt_2)(s+t_2+jt_2)} = \frac{1}{s^2+(2s+1)}$$

(Alternatively, you can postulate a transfer function

$$H(S) = \frac{C}{S^2 + QS + b}$$

and solve for a, b, c to mortch the desired frequency response. You wald have to choose aso, bso to meet the stability regularient.) Additional workspace for Problem 4.

b) Not unique. Multiply with a stable all-pass or shaply multiply by -1 to keep the magnified unchanged.

5. (20 points) When the input to an LTI is:

$$x[n] = \left(\frac{1}{2}\right)^n u[n] + 2^n u[-n-1]$$

the output is:

$$y[n] = 6\left(\frac{1}{2}\right)^n u[n] - 6\left(\frac{3}{4}\right)^n u[n].$$

- a) (10 points) Find the transfer function of H(z) and indicate the region of convergence.
- b) (5 points) Is the system causal? Is it stable?
- b) (5 points) Write the difference equation that characterizes the system.

(Sam)

a). We have

$$X(z) = \frac{1}{1 - \frac{1}{2}z^{-1}} - \frac{1}{1 - 2z^{-1}}$$
(14)

$$= \frac{z}{z - \frac{1}{2}} - \frac{z}{z - 2} \tag{15}$$

$$= \frac{-\frac{3}{2}z}{(z-\frac{1}{2})(z-2)}, \qquad \frac{1}{2} < |z| < 2 \tag{16}$$

$$Y(z) = \frac{6}{1 - \frac{1}{2}z^{-1}} - \frac{6}{1 - \frac{3}{4}z^{-1}}$$
 (17)

$$=\frac{\frac{-3}{2}z}{(z-\frac{1}{2})(z-\frac{3}{4})}, \qquad |z| > \frac{3}{4}. \tag{18}$$

Then

$$H(z) = \frac{Y(z)}{X(z)} = \frac{z - 2}{z - \frac{3}{4}} \tag{19}$$

$$=\frac{1-2z^{-1}}{1-\frac{3}{4}z^{-1}}\tag{20}$$

The ROC of H(z) is either $|z| > \frac{3}{4}$ or $|z| < \frac{3}{4}$. Furthermore, the region of convergence of Y(z) must include at least the intersection of H(z) and X(z), therefore the ROC of H(z) must be

$$|z| > \frac{3}{4}.\tag{21}$$

b). Thus the system is stable (since the ROC includes the unit circle) and causal (since the ROC is the exterior of a circle).

c).

$$y[n] - \frac{3}{4}y[n-1] = x[n] - 2x[n-1]$$
(22)