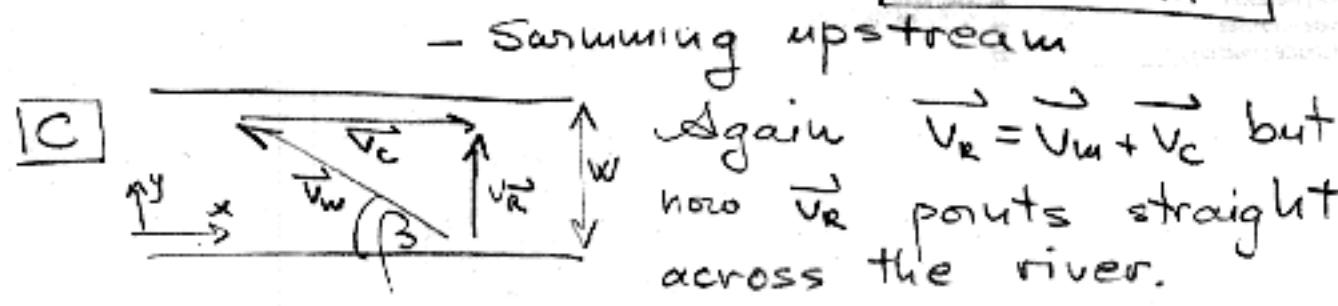


A $x: W = V_m t \rightarrow t = W/V_m$

$y: D = V_r t \rightarrow D = W \frac{V_r}{V_m}$



$y: V_R = V_m \sin \beta$

$x: V_r = V_m \cos \beta \rightarrow \beta = \cos^{-1} V_r / V_m$

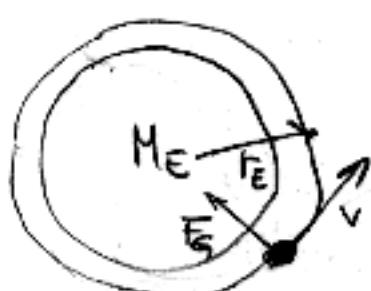
D $y: W = V_R t = V_m \sin \beta t = V_m \sqrt{1 - \cos^2 \beta} t$

$$t = \frac{W}{V_m \sin \beta} = \frac{W}{V_m \sqrt{1 - (\frac{V_r}{V_m})^2}} \quad \boxed{\frac{W}{\sqrt{V_m^2 - V_r^2}}}$$

Problem 2. The only force on the satellite:



"BIRD'S VIEW"
VIEW



$$F_g = G \frac{m M_E}{r_E^2} = mg = m a_{cp} = m \frac{v^2}{r_E}$$

$$mg = m \frac{v^2}{r_E} \quad \boxed{v = \sqrt{g r_E}}$$

- on the surface:

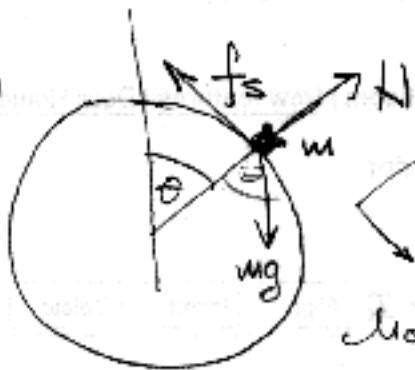
$$F_g = G \frac{m M_E}{r_E^2} = mg = F_g$$

One period:

$$v = \frac{2\pi r_E}{T} = \sqrt{g r_E}$$

$$T = \frac{2\pi r_E}{\sqrt{g r_E}} = 2\pi \sqrt{\frac{r_E}{g}}$$

Problem 3.,



$$y: F_{\text{net}}^y = N - mg \cos \theta$$

$$x: F_{\text{net}}^x = mg \sin \theta - f_s$$

A.

$$N = mg \cos \theta \quad \text{and}$$

$$mg \sin \theta = f_s \leq \mu_s N$$

$$mg = N / \cos \theta \quad \Rightarrow$$

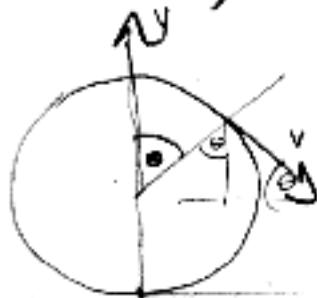
$$mg \sin \theta = \frac{N}{\cos \theta} \tan \theta \leq \mu_s N$$

$$\Rightarrow \tan \theta \leq \mu_s$$

and for max:

$$\theta = \tan^{-1} \mu_s$$

B.



$$\begin{aligned} v_y &= v_0 \sin \theta \\ v_{ox} &= v_0 \cos \theta \\ a_y &= -g \\ a_x &= 0 \end{aligned}$$

$$\begin{aligned} y(t) &= y_0 - v_{oy} t + \frac{1}{2} a_y t^2 \\ &= R(1 + \cos \theta) - v_0 \sin \theta t - \frac{1}{2} g t^2 \end{aligned}$$

$$x(t) = x_0 + v_{ox} t = R \sin \theta + v_0 \cos \theta t$$

$$\text{when } y(t) = 0, \quad D = R \sin \theta + v_0 \cos \theta t$$

$$0 = -R(1 + \cos \theta) + v_0 \sin \theta t + \frac{1}{2} g t^2$$

$$\rightarrow t = \frac{-v_0 \sin \theta + \sqrt{v_0^2 \sin^2 \theta + 2 R g (1 + \cos \theta)}}{g}$$

and distance

$$D = R \sin \theta + v_0 \cos \theta t = R \sin \theta + \frac{v_0 \cos \theta}{g} (v_0 \sin \theta + \sqrt{v_0^2 \sin^2 \theta + 2 R g (1 + \cos \theta)})$$

(where $\mu_s = \tan \theta$,

C. Monkey now accelerates upward with $a_y = a$:



$$x: 0 = F_{\text{net}}^x = -f_s \cos \theta_a + N \sin \theta_a$$

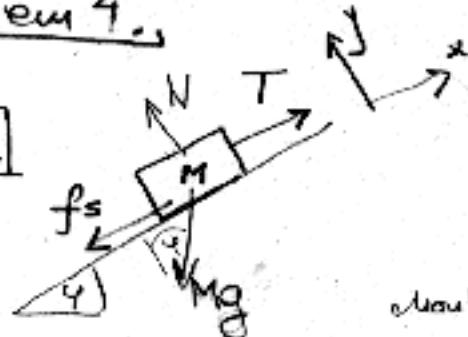
$$\Rightarrow \mu_s N \geq f_s = N \tan \theta_a$$

$$\text{and } \theta_a = \theta = \tan^{-1} \mu_s \quad \mu_s \geq \tan \theta_a \text{ as before}$$

D. The only difference from part B is $a_y = -(g+a)$
therefore $D_a = R \sin \theta + \frac{v_0 \cos \theta}{g+a} (-v_0 \sin \theta + \sqrt{v_0^2 \sin^2 \theta + 2 R (g+a)(1 + \cos \theta)})$

Problem 4.

A.

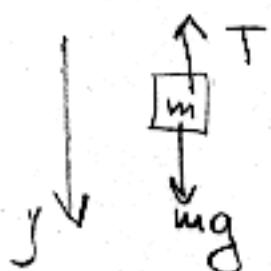


System is @ rest and static friction on M is worked out.

$$\text{monkey: } mg - T = 0$$

$$\text{Box: } T - f_s - Mg \sin \varphi = 0$$

$$N - Mg \cos \varphi = 0$$



$$f_s = T - Mg \sin \varphi = mg - Mg \sin \varphi$$

$$f_s \leq \mu_s N = \mu_s Mg \cos \varphi \implies$$

$$\mu_s Mg \cos \varphi \geq mg - Mg \sin \varphi \quad \text{and system starts moving up if}$$

$$\mu_s < \frac{m - M \sin \varphi}{M \cos \varphi}$$

and

$$m > M \sin \varphi$$

B.

$$\text{monkey: } mg - T = ma$$

$$\text{Box: } T - f_k - Mg \sin \varphi = Ma$$

$$N - Mg \cos \varphi = 0 \implies N = Mg \cos \varphi$$

adding first two equations:

$$mg - f_k - Mg \sin \varphi = (M+m)a, \quad f_k = \mu_k N$$

$$a = \frac{mg - \mu_k Mg \cos \varphi - Mg \sin \varphi}{M+m}$$

$$\text{Kinematics} \quad v_f^2 = v_i^2 + 2ah = 2ah \quad v_f = \sqrt{2ah}$$

$$v_f = \sqrt{\frac{2gh}{M+m}} (m - \mu_k M \cos \varphi - M \sin \varphi)$$