

SECOND MIDTERM OF MATH 54, FALL 2012

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Name: eman (KEY)

SID: DJS

Section and GSI name: eman ISG dna noitceS

Problem	Points Earned	Total Points
1		30
2		15
3		20
4		10
5		25
Total		100

(30 points total) Consider the matrix

$$A = \begin{bmatrix} 1 & a & 1 \\ 0 & -1 & b \\ 0 & 0 & 1 \end{bmatrix}$$

- (10 points) State all necessary conditions, if any, on a, b for A to be invertible. Justify your answer.
- (20 points) State all necessary conditions, if any, on a, b for A to be diagonalizable. Justify your answer.

1. Since A is triangular, $\det A = 1(-1)1 = -1 \neq 0$, so A is invertible for all a, b .

2. Since A is triangular, the eigenvalues of A are 1 and -1 with algebraic multiplicities 2 and 1 .

A will be diagonalizable if and only if the geometric multiplicities of 1 and -1 are 2 and 1 . But since

$1 \leq \text{geom. mult.} \leq \text{alg. mult.}$,
the geometric multiplicity of -1 is always 1 , so we only need to find the geometric multiplicity of 1 , i.e. $\dim \text{Nul}(A - I)$.

$$A - I = \begin{bmatrix} 0 & a & 1 \\ 0 & -2 & b \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{bmatrix} 0 & -2 & b \\ 0 & a & 1 \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_2 \rightarrow R_2 + \frac{a}{2}R_1} \begin{bmatrix} 0 & -2 & b \\ 0 & 0 & 1 + \frac{ab}{2} \\ 0 & 0 & 0 \end{bmatrix}$$

$$\dim \text{Nul}(A - I) = 3 - (\dim \text{Col}(A - I)) = 3 - (\# \text{ of pivots of } A - I),$$

which is 2 only when $1 + \frac{ab}{2} = 0$.

So A is diagonalizable if and only if $1 + \frac{ab}{2} = 0$

ie. $ab = -2$

WARNING: Answers like " $a = -\frac{2}{b}$ " are not completely correct; a and/or b may be 0 , so it does not make sense to divide by them.

(15 points) Find the closest point to y in the subspace W of \mathbb{R}^3 spanned by u_1 and u_2 :

$$y = \begin{bmatrix} -1 \\ 3 \\ 1 \end{bmatrix}, \quad u_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \quad u_2 = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}.$$

Solution #1 $u_1 \cdot u_2 = 0 + 1 + 2 = 3 \neq 0$, so u_1 and u_2 are not orthogonal.
So do Gram-Schmidt to get an orthogonal basis of W :

$$v_1 = u_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}.$$

$$v_2 = u_2 - \frac{u_2 \cdot v_1}{v_1 \cdot v_1} v_1 = u_2 - \frac{0 + 1 + 2}{1 + 1 + 1} v_1 = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} - \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}.$$

Then the closest point is

$$\begin{aligned} \hat{y} = \text{proj}_W \vec{y} &= \frac{y \cdot v_1}{v_1 \cdot v_1} v_1 + \frac{y \cdot v_2}{v_2 \cdot v_2} v_2 = \frac{-1 + 3 + 1}{1 + 1 + 1} v_1 + \frac{1 + 0 + 1}{1 + 0 + 1} v_2 \\ &= \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} = \boxed{\begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}} \end{aligned}$$

Warning: The answer is not:

$$\frac{y \cdot u_1}{u_1 \cdot u_1} u_1 + \frac{y \cdot u_2}{u_2 \cdot u_2} u_2 = \frac{-1 + 3 + 1}{1 + 1 + 1} u_1 + \frac{0 + 3 + 2}{0 + 1 + 4} u_2 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

First, $\| \begin{bmatrix} -1 \\ 3 \\ 1 \end{bmatrix} - \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \| = \| \begin{bmatrix} -2 \\ 1 \\ -2 \end{bmatrix} \| = \sqrt{4 + 1 + 4} = 3$ is bigger than:

$$\| \begin{bmatrix} -1 \\ 3 \\ 1 \end{bmatrix} - \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} \| = \| \begin{bmatrix} -1 \\ 2 \\ -1 \end{bmatrix} \| = \sqrt{1 + 4 + 1} = \sqrt{6}.$$

Second, $\vec{y} - \hat{y}$ needs to be orthogonal to both \vec{u}_1 and \vec{u}_2 ;

$$\begin{bmatrix} -1 \\ 3 \\ 1 \end{bmatrix} - \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \\ -2 \end{bmatrix} \text{ is not orthogonal to } \vec{u}_1.$$

In general, the projection formula does not give the right answer if the starting vectors are not orthogonal.

Solution #2: Want $c_1 \vec{u}_1 + c_2 \vec{u}_2$ where $\begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$ is the least-squares solution to $\begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \end{bmatrix} \cdot \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} -1 \\ 3 \\ 1 \end{bmatrix}$

$$\text{So compute: } A^T A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 3 & 3 \\ 3 & 5 \end{bmatrix}, \quad A^T b = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 5 \end{bmatrix}.$$

$$\begin{bmatrix} 3 & 3 \\ 3 & 5 \end{bmatrix} \xrightarrow{R_2 \rightarrow R_2 - R_1} \begin{bmatrix} 3 & 3 \\ 0 & 2 \end{bmatrix} \xrightarrow{R_1 \rightarrow R_1 - \frac{3}{2} R_2} \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix} \xrightarrow{\substack{R_1 \rightarrow \frac{1}{3} R_1 \\ R_2 \rightarrow \frac{1}{2} R_2}} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}. \text{ So } c_1 = 0, c_2 = 1,$$

$$\text{final answer is } 0 \vec{u}_1 + 1 \vec{u}_2 = \boxed{\begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}}$$

(20 points) Find any orthonormal basis for the inner product on $\mathbb{P}_2(x)$ - i.e. polynomials in x of degree up to 2 - given by

$$\langle p(x), q(x) \rangle = \int_0^1 p(x)q(x) dx.$$

A basis for \mathbb{P}_2 is $\left\{ \underset{u_0}{1}, \underset{u_1}{x}, \underset{u_2}{x^2} \right\}$. We do Gram-Schmidt to get

an orthogonal basis:

$$v_0 = u_0 = 1$$

$$u_1 - \frac{\langle u_1, v_0 \rangle}{\langle v_0, v_0 \rangle} v_0 = u_1 - \frac{\int_0^1 x dx}{\int_0^1 1 dx} v_0 = u_1 - \frac{[\frac{x^2}{2}]_{x=0}^1}{[x]_{x=0}^1} v_0 = x - \frac{1}{2}.$$

Rescale: $v_1 = 2x - 1$

$$u_2 - \frac{\langle u_2, v_0 \rangle}{\langle v_0, v_0 \rangle} v_0 - \frac{\langle u_2, v_1 \rangle}{\langle v_1, v_1 \rangle} v_1 = u_2 - \frac{\int_0^1 x^2 dx}{\int_0^1 1 dx} v_0 - \frac{\int_0^1 (2x^2 - x^2) dx}{\int_0^1 (4x^2 - 4x + 1) dx} v_1$$

$$= u_2 - \frac{[\frac{x^3}{3}]_{x=0}^1}{[x]_{x=0}^1} v_0 - \frac{[\frac{x^4}{2} - \frac{x^3}{3}]_{x=0}^1}{[\frac{4}{3}x^3 - 2x^2 + x]_{x=0}^1} v_1 = u_2 - \frac{1}{3} v_0 - \frac{1}{\frac{1}{3}} v_1 = x^2 - \frac{1}{3} - \frac{1}{2}(2x - 1) = x^2 - x + \frac{1}{6}$$

Rescale: $v_2 = 6x^2 - 6x + 1$

$$\|v_0\| = \sqrt{\int_0^1 1^2 dx} = \sqrt{[x]_{x=0}^1} = \sqrt{1} = 1.$$

$$\|v_1\| = \sqrt{\int_0^1 (2x - 1)^2 dx} = \sqrt{\int_0^1 (4x^2 - 4x + 1) dx} = \sqrt{[\frac{4}{3}x^3 - 2x^2 + x]_{x=0}^1} = \sqrt{\frac{4}{3} - 2 + 1} = \sqrt{\frac{1}{3}} = \frac{1}{\sqrt{3}}$$

$$\|v_2\| = \sqrt{\int_0^1 (6x^2 - 6x + 1)^2 dx} = \sqrt{\int_0^1 (36x^4 + 36x^2 + 1 - 72x^3 + 12x^2 - 12x) dx} = \sqrt{[\frac{36}{5}x^5 - 18x^4 + 16x^3 - 6x^2 + x]_{x=0}^1}$$

$$= \sqrt{\frac{36}{5} - 18 + 16 - 6 + 1} = \sqrt{\frac{36}{5} - 7} = \sqrt{\frac{36}{5} - \frac{35}{5}} = \frac{1}{\sqrt{5}}.$$

So an orthonormal basis is $\left\{ 1, \sqrt{3}(2x - 1), \sqrt{5}(6x^2 - 6x + 1) \right\}$.

(There are others. For example, if you started with $\{x^2, x, 1\}$, you will get $\{\sqrt{5}x^2, \sqrt{3}(5x^2 - 4x), 10x^2 - 12x + 3\}$.)

(10 points) Let $A = \begin{bmatrix} 7 & 2 \\ -4 & 1 \end{bmatrix}$. Find a useful expression for the matrix for A^k , where k is an arbitrary integer > 0 . Hint: Use eigenvalues and eigenvectors.

$$\text{Char. poly. of } A = \begin{vmatrix} 7-\lambda & 2 \\ -4 & 1-\lambda \end{vmatrix} = (7-\lambda)(1-\lambda) + 8 = \lambda^2 - 8\lambda + 7 + 8 \\ = \lambda^2 - 8\lambda + 15 = (\lambda - 3)(\lambda - 5).$$

E-val's of $A =$ roots of Char. poly. of $A = 3, 5$.

$$A - 3I = \begin{bmatrix} 4 & 2 \\ -4 & -2 \end{bmatrix} \sim \begin{bmatrix} 2 & 1 \\ 0 & 0 \end{bmatrix}, \text{ so } \text{Nul}(A - 3I) = \text{Span}\left\{ \begin{bmatrix} -1 \\ 2 \end{bmatrix} \right\}, \text{ e-vec for } \lambda = 3$$

$$A - 5I = \begin{bmatrix} 2 & 2 \\ -4 & -4 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}, \text{ so } \text{Nul}(A - 5I) = \text{Span}\left\{ \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right\}, \text{ e-vec for } \lambda = 5.$$

So if $P = \begin{bmatrix} 1 & 1 \\ -2 & -1 \end{bmatrix}$, then P is invertible and $A = P \begin{bmatrix} 3 & 0 \\ 0 & 5 \end{bmatrix} P^{-1}$

$$\text{so } A^k = P \begin{bmatrix} 3^k & 0 \\ 0 & 5^k \end{bmatrix} P^{-1}$$

$$= \begin{bmatrix} 1 & 1 \\ -2 & -1 \end{bmatrix} \begin{bmatrix} 3^k & 0 \\ 0 & 5^k \end{bmatrix} \left(\frac{1}{-1+2} \begin{bmatrix} -1 & -1 \\ 2 & 1 \end{bmatrix} \right)$$

$$= \begin{bmatrix} 3^k & 5^k \\ -2 \cdot 3^k & -5^k \end{bmatrix} \begin{bmatrix} -1 & -1 \\ 2 & 1 \end{bmatrix}$$

$$= \boxed{\begin{bmatrix} -3^k + 2 \cdot 5^k & -3^k + 5^k \\ 2 \cdot 3^k - 2 \cdot 5^k & 2 \cdot 3^k - 5^k \end{bmatrix}}$$

(25 points total)

- (15 points) Find the equation $y = \alpha_0 + \alpha_1 x$ of the least square line that best fits the data points $(2, 1), (5, 2), (7, 3), (8, 3)$.
- (10 points) For the same data points consider the equation $y = \beta_0 + \beta_1 x + \beta_2 x^2 + \beta_3 x^3 + \beta_4 x^4$ of the best fit least square degree four polynomial. True or false: this has a unique solution. Justify your answer.

1. Want to find all least-squares solutions to $A\vec{x} = \vec{b}$, where

$$A = \begin{bmatrix} 1 & 2 \\ 1 & 5 \\ 1 & 7 \\ 1 & 8 \end{bmatrix}, \quad \vec{x} = \begin{bmatrix} \alpha_0 \\ \alpha_1 \end{bmatrix}, \quad \vec{b} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 3 \end{bmatrix}$$

These are the exact solutions $\hat{\vec{x}}$ to $A^T A \hat{\vec{x}} = A^T \vec{b}$.

$$A^T A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 2 & 5 & 7 & 8 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 3 \\ 3 \end{bmatrix} = \begin{bmatrix} 4 & 22 \\ 22 & 4+25+49+64 \end{bmatrix} = \begin{bmatrix} 4 & 22 \\ 22 & 142 \end{bmatrix}$$

$$\begin{array}{r} 2 \\ 64 \\ 49 \\ +29 \\ \hline 142 \end{array}$$

$$\begin{array}{r} 1 \\ 49 \\ +29 \\ \hline 78 \\ +64 \\ \hline 142 \end{array}$$

$$A^T \vec{b} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 2 & 5 & 7 & 8 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 3 \\ 3 \end{bmatrix} = \begin{bmatrix} 9 \\ 2+10+(7+8)\cdot 3 \end{bmatrix} = \begin{bmatrix} 9 \\ 12+45 \end{bmatrix} = \begin{bmatrix} 9 \\ 57 \end{bmatrix}$$

$$\det(A^T A) = 4 \cdot 142 - 22 \cdot 22 = 4(142 - 11 \cdot 11) = 4(142 - 121) = 4 \cdot 21 = 84,$$

so $(A^T A)^{-1}$ exists and is $\frac{1}{84} \begin{bmatrix} 142 & -22 \\ -22 & 4 \end{bmatrix} = \frac{1}{42} \begin{bmatrix} 71 & -11 \\ -11 & 2 \end{bmatrix}$.

So $\hat{\vec{x}} = (A^T A)^{-1} A^T \vec{b} = \frac{1}{42} \begin{bmatrix} 71 & -11 \\ -11 & 2 \end{bmatrix} \cdot \begin{bmatrix} 9 \\ 57 \end{bmatrix} = \frac{1}{42} \begin{bmatrix} 71 \cdot 9 - 11 \cdot 57 \\ -11 \cdot 9 + 2 \cdot 57 \end{bmatrix}$

Ans: $y = \frac{71 \cdot 9 - 11 \cdot 57}{42} + \frac{-11 \cdot 9 + 2 \cdot 57}{42} x = \frac{71 \cdot 3 - 11 \cdot 19}{14} + \frac{-11 \cdot 3 + 2 \cdot 19}{14} x$

$$= \frac{213 - 209}{14} + \frac{-33 + 38}{14} x = \boxed{\frac{2}{7} + \frac{5}{14} x}$$

2. We need to find all least-squares solutions to $A\vec{x} = \vec{b}$, where

$$A = \begin{bmatrix} 1 & 2 & 2^2 & 2^3 & 2^4 \\ 1 & 3 & 3^2 & 3^3 & 3^4 \\ 1 & 5 & 5^2 & 5^3 & 5^4 \\ 1 & 7 & 7^2 & 7^3 & 7^4 \\ 1 & 8 & 8^2 & 8^3 & 8^4 \end{bmatrix}, \quad \vec{x} = \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \\ \beta_3 \\ \beta_4 \end{bmatrix}, \quad \vec{b} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 3 \end{bmatrix}$$

But A has more columns than rows, so cols of A are dependent, so **FALSE**; there will be infinitely many solutions.

(See Thm. 14 from Ch. 6.)