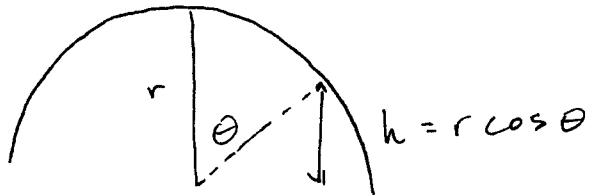


# Yildiz MT 2

#1 / (a) We will use conservation of energy

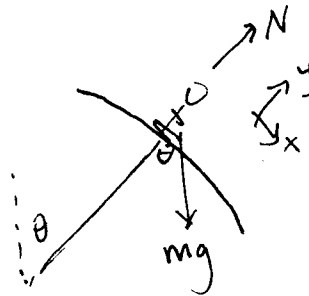


$$E_i = mgr$$

$$E_\theta = mgr \cos \theta + \frac{1}{2}mv^2 \rightarrow \underline{v^2 = 2gr(1 - \cos \theta)} \quad (1)$$

At  $\theta$ , draw FBD

$$\sum F_y = N - mg \cos \theta = -\frac{mv^2}{r}$$



The skier loses contact when  $N = 0$

$$\Rightarrow mg \cos \theta = \frac{mv^2}{r} \rightarrow v^2 = rg \cos \theta \quad (2)$$

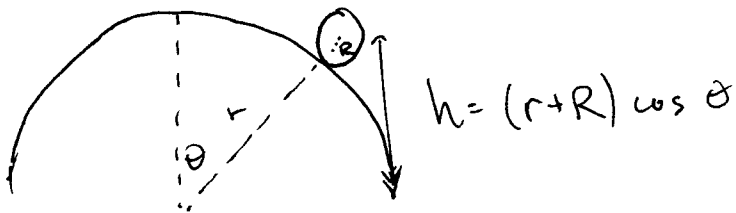
Combining (1) & (2)

$$rg \cos \theta = 2gr(1 - \cos \theta) \rightarrow 3 \cos \theta = 2$$

$$\cos \theta = \frac{2}{3} \quad \omega \quad \boxed{\theta = 48.2^\circ}$$

# Yildiz MT 2

#1 / (b) Now we have a ring,  $I_{ring} = mR^2$



Again we use energy conservation

$$E_i = mg(r+R)$$

$$E_\theta = mg(r+R) \cos \theta + \frac{1}{2} m v_{cm}^2 + \frac{1}{2} I \omega^2$$

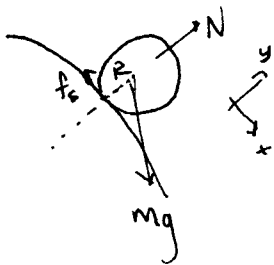
Since it rolls without slipping,  $\omega = v_{cm}/R$ .

Plug in  $I_{ring}$  & set  $E_i = E_\theta$ :

$$mg(r+R) = mg(r+R) \cos \theta + \frac{1}{2} m v_{cm}^2 + \frac{1}{2} m R^2 \left( \frac{v_{cm}}{R} \right)^2$$

$$\Rightarrow v_{cm}^2 = g(r+R)(1 - \cos \theta). \quad (1)$$

FBD:



$$\sum F_y = N - mg \cos \theta = -\frac{m v_{cm}^2}{r+R} \xrightarrow{N=0} v_{cm}^2 = (r+R) g \cos \theta \quad (2)$$

Combine (1) & (2)

$$g(r+R)(1 - \cos \theta) = (r+R) g \cos \theta$$

$$\cos \theta = 1/2 \rightarrow \boxed{\theta = 60^\circ}$$

# Yildiz midterm 2

## Problem 2.

Solution:

(i) For part (a) and (b), no friction

$$E_k + E_p = \text{constant}.$$

$$\Delta E_k + \Delta E_p = 0 \Rightarrow \Delta E_p = -\Delta E_k = 0$$

So we have  $E_{pi} = E_{pf}$ .

$$E_{pi} = \frac{1}{2}k(\Delta x_0)^2 = \frac{1}{2} \times 80 \times 0.5^2 = 10 \text{ (J)}$$

$$(a) \quad E_{pf} = mgL \sin \theta$$

$$\text{so } L = \frac{E_{pf}}{mg \sin \theta} = \frac{E_{pi}}{mg \sin \theta} = \frac{10}{1.8 \times 9.8 \times 0.6} = 0.9 \text{ (m)}$$

$$(b) \quad E_{pf} = mgL \sin \theta + \frac{1}{2}k(L - \Delta x_0)^2$$

where  $\Delta x_0$  is the initial compression

$$\Delta x_0 = 1.00 \text{ m} - 0.5 \text{ m} = 0.5 \text{ m}$$

$$\text{so } E_{pi} = E_{pf} = mgL \sin \theta + \frac{1}{2}k(L - \Delta x_0)^2$$

Plug in numbers, we get

$$10 = 1.8 \times 9.8 \times 0.6 L + \frac{1}{2} \times 80 \times (L - 0.5)^2$$

↓

$$40L \left( L - 1 + \frac{1.8 \times 9.8 \times 0.6}{40} \right) = 0$$

$L \neq 0$  (we are interested in the solution  $L > 0.5\text{m}$ )

$$\text{So } L = 1 - \frac{1.8 \times 9.8 \times 0.6}{40} = 0.7 \text{ (m)}$$

(2) For part (c)

$$W_f = \Delta E_k + \Delta E_p$$

$$\Delta E_k = 0$$

$$\Delta E_p = \Delta E_{p,s} + \Delta E_{p,g}$$

$$= -\frac{1}{2} k (\Delta x_0)^2 + mg \Delta x_0 \sin \theta$$

$$\text{So } W_f = -\frac{1}{2} k (\Delta x_0)^2 + mg \Delta x_0 \sin \theta$$

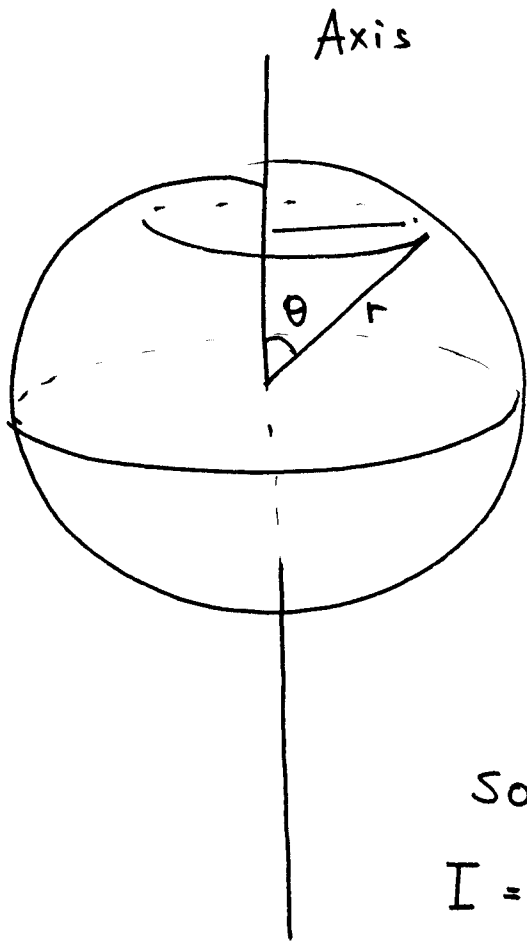
$$\text{On the other hand } W_f = -\mu_k mg \cos \theta \Delta x_0$$

$$\text{So } -\mu_k mg \cos \theta \Delta x_0 = -\frac{1}{2} k (\Delta x_0)^2 + mg \Delta x_0 \sin \theta$$

$$\mu_k = \frac{\frac{1}{2} k \Delta x_0 - mg \sin \theta}{mg \cos \theta} = \frac{\frac{1}{2} \times 80 \times 0.5 - 1.8 \times 9.8 \times 0.6}{1.8 \times 9.8 \times 0.8} = 0.7$$

3

a)



$$\int (r \sin \theta)^2 dm = I.$$

$$\begin{cases} dm = \rho dV, & \rho = \frac{\mu}{\frac{4}{3}\pi R^3} \\ dV = r^2 \sin \theta dr d\theta d\phi. \end{cases}$$

So,

$$\begin{aligned} I &= \rho \int_0^{R_0} dr \int_0^\pi d\theta \int_0^{2\pi} d\phi r^4 \sin^3 \theta \\ &= 2\pi \rho \frac{R_0^5}{5} \int_0^\pi d\theta \sin^3 \theta \end{aligned}$$

$$\int_0^\pi d\theta \sin^3 \theta = \int d \cos \theta (\cos^2 \theta - 1)$$

$$= \frac{4}{3}$$

thus, 
$$I = 2\pi \frac{\mu}{\frac{4}{3}\pi R^3} \cdot \frac{R^5}{5} \times \frac{4}{3} = \frac{2}{5} \mu R^2$$

3

b)

Without slipping :  $R_0 \omega = v$ .

and

total kinetic energy

$$= (\text{translational}) + (\text{rotational})$$

$$= \frac{1}{2} M v^2 + \frac{1}{2} \times \frac{2}{5} M R_0^2 \omega^2$$

$$= \frac{1}{2} M v^2 + \frac{1}{5} M v^2 = \frac{7}{10} M v^2.$$

at the highest point in the circle,

$$V = h_{cm} M g = (2R - R_0) M g.$$

due to the energy conservation,

$$M g (2R + Y - R_0) = (2R - R_0) M g + \frac{7}{10} M v^2$$

$$\therefore M g Y = \frac{7}{10} M v^2.$$

$$\text{and thus, } v^2 = \frac{10}{7} g Y.$$

not to fall at the highest point,

$$M \frac{v^2}{R - R_0} \geq M g \quad \therefore Y \geq \frac{7}{10} (R - R_0).$$

# Yildiz MT 2 #4

The equation we need is

$$M \frac{d\vec{v}}{dt} = \sum \vec{F}_{\text{ext}} + \vec{v}_{\text{rel}} \frac{dM}{dt}$$

The external force is due to gravity:

$$F_g = -\frac{M_E m G}{(R_E + h)^2} = -\frac{M_E m G}{4R_E^2} = -m \frac{g}{4}$$

(the altitude  $h$  is numerically equal to  $R_E$  for this problem)

where  $g = \frac{GM_E}{R_E^2} \sim 10 \text{ m/s}^2$ . Let  $m = 2.4 \cdot 10^4 \text{ kg}$ ,  $a = 1.5 \text{ m/s}^2$ ,  $v_{\text{rel}} = 1.3 \frac{\text{km}}{\text{s}}$

and  $R = \left| \frac{dM}{dt} \right|$ . Our equation is now just

$$ma = -\frac{mg}{4} + v_{\text{rel}} R$$

$$\rightarrow R = \frac{m(a + g/4)}{v_{\text{rel}}} = \boxed{76.9 \text{ kg/s}}$$

5) (a) Linear momentum is conserved,

$$\Rightarrow mv_0 = mv_f + mv_{cm}$$

$$\Rightarrow v_{cm} = v_0 - v_f \quad - (1)$$

} 2 Marks

Angular momentum is conserved,  $\rightarrow$  1 mark

$$\Rightarrow mv_0 l = I_{cm} \omega_f + mv_f l \quad \rightarrow 1 \text{ mark}$$

$$I_{cm} = \frac{M(2l)^2}{12} = \frac{Ml^2}{3} \quad \rightarrow 1 \text{ Mark}$$

$$\Rightarrow v_0 = \frac{\omega_f l}{3} + v_f \Rightarrow \omega_f l = 3(v_0 - v_f) \quad - (2)$$

Energy is conserved,

$$\Rightarrow \frac{1}{2} mv_0^2 = \frac{1}{2} I_{cm} \omega_f^2 + \frac{1}{2} mv_f^2 + \frac{1}{2} mv_{cm}^2 \quad \left. \vphantom{\frac{1}{2} mv_0^2} \right\} 3 \text{ Marks}$$

$$\Rightarrow v_0^2 = \frac{(\omega_f l)^2}{3} + v_f^2 + v_{cm}^2 \quad - (3)$$

Substituting (1), (2) in (3), we get

$$v_f = \left( v_0, \frac{3v_0}{5} \right)$$

neglected

} 4 Marks  
for math  
and final answer

$$\text{Hence } \boxed{v_f = \frac{3v_0}{5}}$$

(b) As the rod is fixed, Linear momentum is not conserved and rotation takes abt the pivoted point.

$$\text{Hence } I \text{ to be considered} = I_{end} = \frac{M(2L)^2}{12} + \frac{M(L)^2}{3} = \frac{4ML^2}{3}$$

- 1 Mark

$\rightarrow$  Angular momentum is conserved,

$$mv_0(2l) = I_e \omega_f + mv_f(2l)$$

$$\Rightarrow \omega_f l = \frac{3}{2}(v_0 - v_f) \quad - (4)$$

} 2 Marks

$\rightarrow$  Energy is conserved,

$$\frac{1}{2} mv_0^2 = \frac{1}{2} mv_f^2 + \frac{1}{2} I_e \omega_f^2$$

$$\Rightarrow v_0^2 = v_f^2 + \frac{4}{3}(\omega_f l)^2 \quad - (5)$$

} 2 Marks

Solving for  $v_f$  from (4) and (5), we get

$$\boxed{v_f = \frac{v_0}{2}}$$

} 3 Marks for  
math and final  
answer.