Mechanics of Materials (CE130-II)

The First Mid-term Examination (Spring 2004)

Problem 1.

Consider the following statically indeterminate system (Fig. 1). Find the reactions forces R_1 and R_2 . Hint: The flexibility is defined as

$$f = \frac{L}{EA},\tag{1}$$

and relationship between internal force and elongation of a two force bar is $P = f\Delta$.

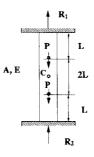


Figure 1: A Statically Indeterminate System

Problem 2

Consider the following two shaft system. Both shafts have circular cross section. Find the maximum shear stress in the system. Assuming $T_B = T$ and $T_C = 2T$. The radius of shaft AB is given as R = C; and the radius of shaft BC is given as R = 2C. Hints: torsion formula

$$\tau = \frac{T\rho}{I_{\rho}}$$
, for shafts with circular cross section , $I_{\rho} = \frac{\pi R^4}{2}$. (2)

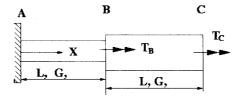


Figure 2: Torsion of a two-shaft system

Problem 3

A planar circular three-hinge arch consists of two segments as shown in Fig. 3. Determine the reaction forces at A and B caused by the application of a vertical force P.

Problem 4

Consider a long (1000 meters in z-direction) concrete block with its both ends fixed. The cross section of the concrete block (section in x-y plane) is a 5 meter square. Suppose that in x-y plane,

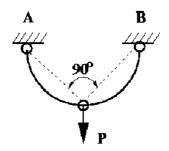


Figure 3: A two-bar truss system

the block is subjected biaxial tensile stress load, namely, $\sigma_x = 5MP_a$ and $\sigma_y = 10MP_a$. This is a typical plane strain state. Let $E = 100MP_a$ and Poisson's ratio $\nu = 0.3$. Find σ_z , ϵ_x , and ϵ_y . Hint: The generalized Hooke's law is

$$\begin{array}{rcl} \epsilon_x & = & \frac{\sigma_x}{E} - \nu \frac{\sigma_y}{E} - \nu \frac{\sigma_z}{E} \\ \epsilon_y & = & -\nu \frac{\sigma_x}{E} + \frac{\sigma_y}{E} - \nu \frac{\sigma_z}{E} \\ \epsilon_z & = & -\nu \frac{\sigma_x}{E} - \nu \frac{\sigma_y}{E} + \frac{\sigma_z}{E} \end{array}$$

Problem 5.

Consider a rectangular block with the dimension $dx \times dy \times dz$. Uniform shear stress, τ_{xy} , is acting on the surfaces normal to (+/-) x-axis and uniform shear stress, τ_{yx} , is acting on the surfaces normal to (+/-) y-axis as shown in Figure 4. Show $\tau_{xy} = \tau_{yx}$. Hint: use moment equilibrium equation about the z-axis $(\sum M_z = 0)$.

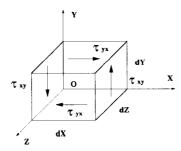
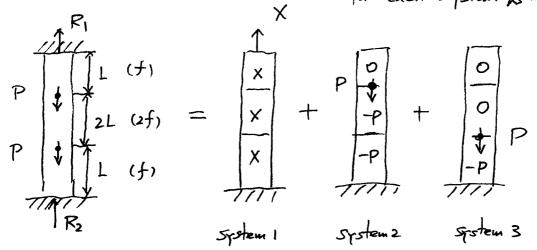


Figure 4: Infinitesimal element in pure shear

Solutions - for practice Mid-term Exam

Problem 1.

Use superposition method: We first mark the internal force for each system as follow:



Then

$$\Delta^{(1)} = f \times + 2f \times + f \times = 4f \times$$

$$\Delta^{(2)} = 0 - 2f P - f P = -3f P$$

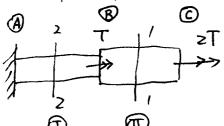
$$\Delta^{(3)} = 0 + 0 - f P = -f P$$

$$\Delta^{(1)} + \Delta^{(2)} + \Delta^{(3)} = 4f \times - 4f P = 0$$

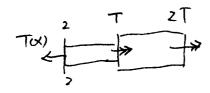
$$X = P = R_1$$

Problem 2

We first find internal torque diagram:

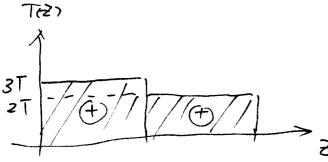


$$-Tay+2T=0$$



$$ZM_2 = 0$$

$$-T(2) + T + 2T = 0$$

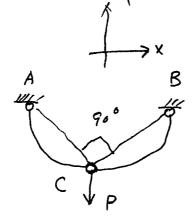


$$T_{\text{max}} = \frac{3T \cdot C}{(\pi C^4)/2} = \frac{6T}{\pi C^3}$$

$$T_{\text{max}} = \frac{3T \cdot C}{(\pi C^4)/2} = \frac{6T}{\pi C^3}$$
, $T_{\text{max}} = \frac{2T \cdot 2C}{\pi (2C)^4/2} = \frac{T}{2\pi C^3}$

The maximum shear stress is :

Problem 3



The free-body diagram of the joint is (since both AC&BC ark two-force members)

$$N \ge F_A = P \Rightarrow F_A = F_B = \frac{P}{N \ge}$$

Problem 4.

(1) Plane strain Ezz=0

$$\Rightarrow -v\frac{\sigma_{XX}}{E} - v\frac{\sigma_{YY}}{E} + \frac{\sigma_{ZZ}}{E} = 0$$

$$\sigma_{ZZ} = v(\sigma_{XX} + \sigma_{YY}) = 0.3 \times (5 + 10) = 0.3 \times 15 \quad MP_{a}$$

$$= 4.5 \quad MP_{a}$$

(2)
$$E_{X} = \frac{\nabla x}{E} - \nu \frac{\nabla x}{E} - \nu \frac{\nabla x}{E} = \frac{1}{E} (5 - 0.3 \times 10 - 0.3 \times 4.5)$$

$$= 0.65 \times 10^{8} = 0.0065 \quad \mu \text{ strain}$$

$$\begin{aligned}
& \in_{\Upsilon} = \frac{1}{E} \left(- \nu \nabla_{XX} + \nabla_{\Upsilon} - \nu \nabla_{22} \right) \\
& = \left(- 6.3 \times 5 + 10 - 0.3 \times 4.5 \right) \times 10^{-8} = 7.15 \times 10^{-8} \\
& = 0.07 \quad \mu \text{ strain}
\end{aligned}$$

Problem 5

Take a moment around 2-axis

$$\frac{(x_T dzd_T) \cdot dx}{F_T} - \frac{dx}{F_X} = 0$$

$$\frac{F_T}{F_X} arm$$